IN THE SPECIFICATION

Please replace the paragraph beginning at page 4, line 4, with the following rewritten paragraph:

A very suitable driving arrangement is obtained if the drive means comprise an electric dector motor for each supporting surface. In general, such an electric motor will form part of each supporting unit. The electric power supply thereof may take place by means of a battery, via electric sliding contact or via contactless energy transfer, for example.

Please replace the paragraph beginning at page 18, line 1, with the following rewritten paragraph:

· Figs. 19 and 20 schematically show a neutral position and an extreme position of means for tilting a supporting surface [[66]] 36. The supporting surface 36 is supported by a supporting body 50, which is capable of tilting movement about the axis 51. The supporting body 50 is provided with a camway 52, which extends radially and (at least in the neutral position that is shown in Figs. Fig. 19) vertically relative to the axis 51. A camming member 53 extends within the camway 52, which camming member is connected to the arm 54, of which the end remote from the camming member 53 is rotatable about an axis of rotation 55. Rotation about the axis of rotation 55 may take place both to the right and to the left. Upon rotation to the right, the situation as shown in Fig. 20 is reached in an extreme position, in which position the angle between the connecting line between the axis 51 and a camming member 53 on the one hand and the connecting line between the camming member 53 and the axis of rotation 55 on the other hand is approx. 90 degrees. The advantages of this have

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already been explained in the foregoing.